17CS41E1 -INTRODUCTION TO ROBOTICS AND NAVIGATION

|  |  |  |  |
| --- | --- | --- | --- |
| **Course Category:** | Professional Elective | **Credits:** | 3 |
| **Course Type:** | Theory  | **Lecture – Tutorial – Practical:** | 3-0-0 |
| **Prerequisite:** | Basics of probability and statistics, and Artificial intelligence concepts are required. | **Sessional Evaluation:****Univ. Exam Evaluation:****Total Marks:** | 4060100 |
| **Objectives** | * To Learn about the Basics of Robotics and its Teleoperations.
* Identify the Hierarchical Paradigm and its Functionalities.
* To evaluate the Performance of different Navigation Models.
 |

|  |  |
| --- | --- |
| **Course Outcomes** | Upon the successful completion of the course, the students will be able to: |
| CO1 | Understand the evolution of Robotics and important areas of AI. |
| CO2 | Learn the Hierarchical Paradigm, Biological Foundations ofReactive Paradigm and its Importance . |
| CO3 | Know the Reactive Paradigm, Designing and its Implementation. |
| CO4 | Explore the Behavioral, Sensing Techniques for Reactive Robots. |
| CO5 | Analyze the Attributes, Architectural Aspects of Reactive Paradigm. |
| CO6 | Specify the Relational Methods, Associative Methods of Topological Path Planning and Objectives and Overview of Metrics Path Planning**.** |
| **Course Content** | **UNIT – I****Teleoperation To Autonomy**: How can a Machine Be Intelligent, What can Robots Be Used For, A Brief History of Robotics, Teleoperation, The Seven Areas of AI.**UNIT – II****Hierarchical Paradigm:** Representative Architectures, Advantages and Disadvantages**.** **Biological Foundations Of The Reactive Paradigm:** What are Animal Behaviors, Coordination and Control of Behaviors, Perception in Behaviors, Schema Theory.**UNIT – III****Reactive Paradigm:** Attributes of Reactive Paradigm, Subsumption Architectures.**Designing A Reactive Implementation**: Behaviors as Objects in OOP, Steps in Designing a Reactive Behavioral System.**UNIT – IV****Common Sensing Techniques for Reactive Robots:** Behavioral sensor Fusion, Designing a Sensor Suite, Proprioceptive Sensors, Proximity Sensors, Computer Vision.**UNIT – V****Hybrid Deliberative/Reactive Paradigm:** Attributes of the Hybrid Paradigm, Architectural Aspects, Managerial Architectures, State-Hierarchy Architectures, Model-Oriented Architectures, Other Robots in the Hybrid Architectures, Interleaving Deliberation and Reactive Control**.****UNIT – VI****Topological Path Planning:** Landmarks and Gateways, Relational Methods, Associative Methods, Case Study of Topological Navigation with a Hybrid Architecture.**Metrics Path Planning**: Objectives and Overview, Configuration Space, Cspace Representations, Graph Based Planners, Wavefront Based Planners. |
| **Text Books and References:** | **Text Books:** 1. Introduction To AI Robotics, Robin R Murphy.**Reference Books:**[From AI to Robotics: Mobile, Social, and Sentient Robots, Bhaumik & Arkapravo.](http://b-ok.cc/book/3496299/f0afb0)1. [Behavior Trees in Robotics and AI. An Introduction,[Michele Colledanchise](http://b-ok.cc/g/Michele%20Colledanchise), [Petter Ögren](http://b-ok.cc/g/Petter%20%C3%96gren)](http://b-ok.cc/book/3561341/d6ac10)
 |
| **E-Resources** | 1. <https://nptel.ac.in/courses>
2. <https://freevideolectures.com/university/iitm>
 |